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Patent Search

Invention Title	OTIC AND MAP LEAD METAOT AND AI IMAGE PROCESSING BASED ROB VEHICLE TO IDENTIFYL CONCENTRATION IN AGRICULTURAL SO
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Abstract:

This invention is a robotic vehicle that identifies and map lead metal concentration in agricultural soil employing a camera. The data from the camera are collected at time stamp and sent to the server dedicated for this product via the Internet employing an IoT Module. This soil type will be detected with the image data collected from camera. Next the camera sensor identifies whether the soil has lead content or not. If lead content is found in the soil collected it maps the lead metal concentration in agricultural soil. The Machine learning model is trained by providing various images of soil with lead metal concentration. The entire robot can be made to traverse in a programmed route in a field to collect data from throughout. A trained Ensemble Machine Learning model for soil information inference from the data collected from mentioned above is loaded at the centralized server. The data collected from different soils is first categorized and employed to train the ensemble machine learning model. The model is trained, it can operate as a reliable predictive model. A combination of Convolutional Neural Network, Support Vector Machine, Linear Regression and K-Nearest Neighbors is employed for the above said ensemble machine learning model.

Complete Specification

Field of Invention. IoT Application in Agriculture

* Background Art including citations of prior art: There are no IOT And AI Image Processing based robotic vehicle to Identify and Map Lead Metal Concentration in Agricultural Soil as presented in this invention.

*Objective of invention (the invention's objectives and advantages, or alternative embodiments of the invention):The objective of the invention is to employ multiple sensor data fusion technique integrated with ensemble machine learning model to identify and map lead metal concentration in agricultural soil. The collected data from the sensor is sent to the server and the ensemble machine learning training performed

* Summary of Invention:

This invention is a robotic vehicle that identifies and map lead metal concentration in agricultural soil employing a camera. The soil is first collected from the agricultural land using a cup and stirred periodically using a stirrer. The data from the camera are collected along with a time stamp and sent to the server dedicated for this product via the Internet employing an IoT Module. The camera sensor first detects the type of the soil with the colour as primary parameter. The soil can be red soil, black soil or other such types. This soil type will be detected with the image data collected from the camera. Next the camera sensor identifies whether the soil has lead content

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Application Details

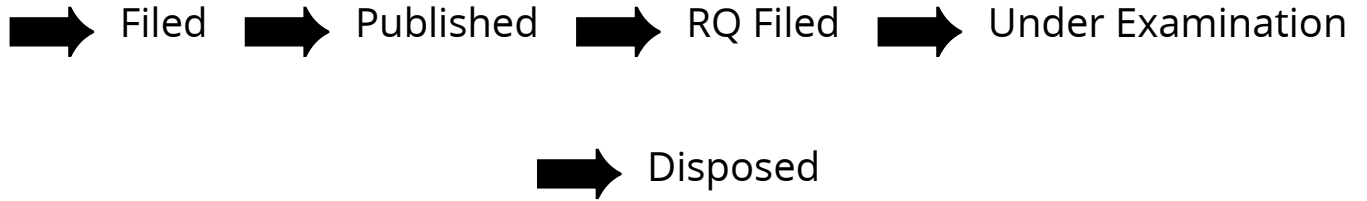
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APPLICATION STATUS

Awaiting Request for Examination

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