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INSTITUTE OF AERONAUTICAL ENGINEERING (Autonomous)

B.Tech IV Semester End Examinations (Regular/Supplementary) - July, 2021

Regulation: R18

ELECTRICAL MACHINES-II

Time: 3 Hours

(EEE)

Max Marks: 70

Answer FIVE Questions choosing ONE question from each module
(NOTE: Provision is given to answer TWO questions from any ONE module)

All Questions Carry Equal Marks

All parts of the question must be answered in one place only

UNIT – I

- (a) Why is it impossible for the rotor of an induction motor to rotate at the same speed as that of the magnetic field? Explain in detail. [7M]
(b) Briefly discuss the principle of constant magnetic field and pulsating magnetic fields. [7M]
- (a) Describe how the rotating magnetic field is produced by three-phase currents with suitable phasor diagrams.. [7M]
(b) Explain the construction and principle of operation of 3-phase induction motor with neat diagrams. [7M]

UNIT – II

- (a) Explain auto-transformer and rotor resistance starting methods for starting slip ring induction motor. [7M]
(b) An 8 pole, three phase alternator is coupled to a prime mover running at 750 rpm. It supplies an induction motor which has a full load speed of 960 rpm. Find the number of poles of induction motor and slip. [7M]
- (a) Derive torque equation of induction motor and find the relation between full load torque to maximum torque and starting torque to full load torque. [7M]
(b) Two 50Hz 3 phase induction motor having 6 and 4 pole respectively are cumulative cascaded, the 6 pole motor being connected to main supply. Determine the frequency of the rotor currents and slips referred to each stator field if the set has a slip of 2%. [7M]

UNIT – III

- (a) Define armature reaction and explain the effect of armature reaction on different power factor loads of synchronous generators. [7M]
(b) Derive an expression for induced emf in an alternator, distribution factor and coil span factor. [7M]
- (a) What is voltage regulation of an alternator? Describe synchronous impedance method of determining regulation of the alternator. [7M]
(b) A 2200V 50Hz 3 phase star connected alternator has an effective resistance of 0.5 ohm per phase. A field current of 30A, full load current of 200A on short circuit and a line-to-line emf of 1100V on open circuit. Determine the power angle of the alternator when it delivers full-load at 0.8pf lagging. [7M]

UNIT – IV

7. (a) Derive the expression for power developed in a synchronous motor. Also find the condition for maximum power developed. [7M]
- (b) A 6600V 3 phase star connected synchronous motor draws a full load current of 80A at 0.8 pf leading. The armature resistance is 2.2 ohm and reactance 22 ohm per phase. If the stray loss are 3200W, calculate emf induced, output power and efficiency of the machine. [7M]
8. (a) Explain the construction and working principle of synchronous motor. [7M]
- (b) The excitation of a 400V, 3 phase mesh connected synchronous motor is such that the induced emf is 510V. The impedance per phase is $(0.6+j4.5)$. If the friction and iron loss 800W, calculate line current, output power, power factor and efficiency at maximum power output. [7M]

UNIT – V

9. (a) Why is a single phase induction motor unable to start itself without special auxiliary windings? Justify your answer with double revolving field theory. [7M]
- (b) The following test result was obtained in case of a 220V single phase induction motor. No load test : 220V, 5.8A, 310W Locked rotor test 120V, 13.8A, 530W. Determine the approximate equivalent circuit parameters of the motor. [7M]
10. (a) Explain what is meant by capacitor start and split phase method of starting a single phase induction motor. [7M]
- (b) The following data pertains to a single phase induction motor. No of poles 4, supply voltage 110V, rated output 140W, slip at rated output is 5%, total copper loss at full load 28W, rotational loss is 28W. Calculate the efficiency and rotor copper loss caused by the backward field. Neglect stator copper loss. [7M]

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