



INSTITUTE OF AERONAUTICAL ENGINEERING

(Autonomous)

B.Tech IV Semester End Examinations (Regular / Supplementary) - May 2019

Regulation: IARE – R16

CONTROL SYSTEMS

Time: 3 Hours

(Common to ECE | EEE)

Max Marks: 70

Answer ONE Question from each Unit

All Questions Carry Equal Marks

All parts of the question must be answered in one place only

UNIT – I

1. (a) Compare closed loop control system with open loop control system. [7M]
- (b) Obtain the transfer function for the given mechanical system shown in Figure 1. [7M]

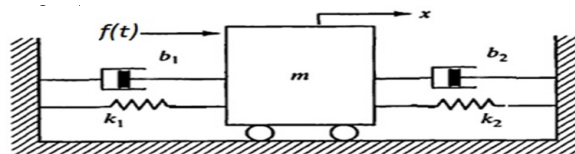


Figure 1

2. (a) How mechanical translational and rotational systems are modeled by ideal elements? Briefly discuss. [7M]
- (b) Human being is an example of closed loop system. Justify your answer? [7M]

UNIT – II

3. (a) Deduce the transfer function for armature control of DC Servo motor. [7M]
- (b) Find the transfer function for the block diagram shown in Figure 2. [7M]

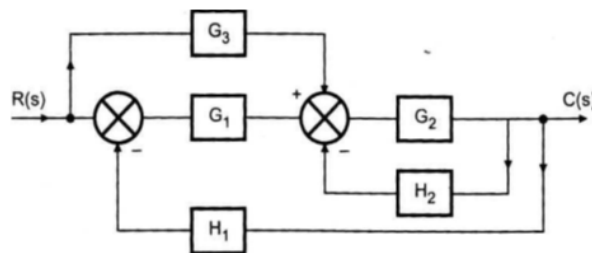


Figure 2

4. (a) Explain briefly about Mason's gain formula? What are the advantages of signal flow graph over block diagram technique? [7M]
 (b) Obtain the transfer function for the signal flow graph, shown in Figure 3 [7M]

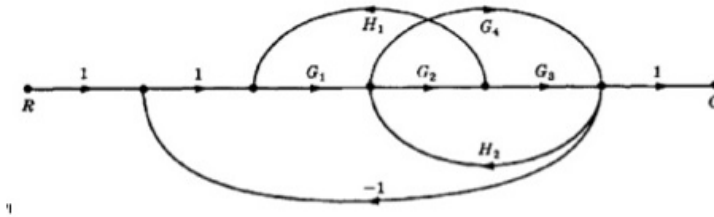


Figure 3

UNIT – III

5. (a) Discuss about the special cases while checking stability in Routh-Hurwitz criterion with an example. [7M]
 (b) Check the stability of the given characteristic equation using Routh's method? [7M]
 $S^6 + 2S^5 + 8S^4 + 12S^3 + 20S^2 + 16S + 16 = 0$
6. (a) Define the terms (i) Absolute stability (ii) Marginal stability (iii) Conditional stability [7M]
 (b) Draw the root locus plot for $G(S)H(S)=K/S(S+1)(S+3)$ and comment on stability. [7M]

UNIT – IV

7. (a) What is frequency response? What are advantages of frequency response analysis? [7M]
 (b) Sketch bode plot of a system $G(s) * H(S)=1/((1+s)(1+2s))$ [7M]
8. (a) Define the following terms i) Gain cross over frequency ii) Resonant peak iii) Resonant frequency [7M]
 (b) Calculate the resonant peak and resonant frequency for the system whose transfer function is $C(S)/R(S)=5/S^2+2S+5$ [7M]

UNIT – V

9. (a) Explain the state variable and state transition matrix and write short notes on formulation of state equations. [7M]
 (b) Determine the output of the system with zero initial state $\dot{X} = \begin{pmatrix} 2 & 0 \\ 0 & 4 \end{pmatrix} X + \begin{bmatrix} 1 \\ 1 \end{bmatrix} U,$
 $Y = [4 \ 0]X$ excited through unit impulse input. [7M]
10. (a) Write short notes on canonical form of representation. List its advantages and disadvantages? [7M]
 (b) Design a lead compensator for the system with open loop transfer function $G_f = \frac{K}{S(1+0.1S)}$ for the specifications, $K_a = 10$ and $\phi_{PM} = 30^\circ$. [7M]

